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The IronTract challenge: Validation and optimal tractography methods for the HCP diffusion acquisition scheme

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Synopsis

We present results from IronTract, the first challenge to evaluate tractography on the two-shell diffusion scheme of the Human Connectome Project (HCP). Accuracy was evaluated by comparison to tracer injections in the same macaque brains as the diffusion data. Training and validation datasets involved different injection sites. We observed that optimizing data analysis with respect to one injection site does not guarantee optimality for another; encouragingly, two teams could achieve consistently high performance in both datasets. We also found that, when analysis methods are optimized, the HCP scheme may achieve similar accuracy as a more demanding diffusion spectrum imaging acquisition.

Introduction

The error-prone nature of diffusion MRI (dMRI) tractography has received considerable attention in recent years, in great part due to tractography challenges that have increased our awareness of the limitations of this technique¹⁻⁷. Prior challenges, however, used dMRI data that had been either synthesized or acquired with a single, low b-value. This precluded the use of state-of-the-art analysis methods that require multi-shell or Cartesian sampling schemes. Furthermore, it is not clear whether the conclusions of those studies are applicable to the multi-shell, high-angular-resolution dMRI data that are now widely available thanks to large-scale initiatives like the Human Connectome Project (HCP). The IronTract challenge seeks to address this gap by investigating i) which data processing strategies lead to optimal tractography accuracy for the two-shell dMRI acquisition scheme of the lifespan and disease HCP, and ii) whether those methods could achieve even higher accuracy with a different acquisition scheme. Here we present initial results of the challenge and discuss next steps.

Methods

The training and validation cases are part of a previously described dataset that consists of in-vivo tracing and ex-vivo dMRI acquired in the same macaque brains⁸⁻¹⁰. **Tracer data:** Bidirectional tracers were injected as previously described¹¹. The training and validation cases consisted of two different brains each of which received a single injection, in the anterior frontal and ventrolateral prefrontal cortex respectively. **dMRI data:** After fixation, the brains were scanned in a small-bore 4.7T Bruker scanner using 3D EPI, (0.7x0.7x0.7mm, TR=750ms, TE=43ms, $\delta=15$ ms, $\Delta=19$ ms, maximum $b=40,000$ s/mm²), with 515 volumes corresponding to a Cartesian lattice in q-space. These data were resampled on q-space shells, using a fast implementation of the non-uniform fast Fourier transform (NUFFT)¹². We generated data on the two q-shells of the HCP lifespan acquisition scheme ($b=1500/3000$ s/mm², multiplied here by the 4x factor required to achieve comparable diffusion contrast ex-vivo as in-vivo¹³). **Challenge:** The challenge was administered through the QMENTA platform (qmenta.com/irontract-challenge/). Participants were blind to the tracer data. For the training case, they uploaded their tractography results and received a score (see below) and ranking. They could repeat this any number of times while they fine tuned the free parameters of their methods to optimize their score. They then applied their optimized analysis pipelines to the validation case, which was used as the basis for the final ranking (Figure 1). **Figure of merit:** In contrast to prior challenges, participants were asked to upload tractography volumes obtained with multiple thresholds. The thresholding strategy (e.g., angle or probability-based) was left up to the participants. For each tractography volume, true and false positive rates were computed by voxel-wise comparison to the tracer data. The score was the area under the curve (AUC). It was computed for false positive rates in [0,0.3], hence the maximum score was 0.3. We separated the rankings into: i) **Overall/DSI:** participants were allowed to use any sampling scheme ii) **HCP:** participants were restricted to the HCP-like, two-shell scheme.

Results

We report results submitted before the MICCAI 2019 conference. Out of 30 registered teams, 12 completed the challenge. There were 227 total submissions (training: 187, validation: 39) and 17 final submissions that were ranked. The diffusion reconstruction and tractography algorithms used are reported in Table 1. Overall, better performance was achieved for the training (mean AUC=0.20) than the validation case (mean AUC=0.15) (Figure 2). Higher AUC scores were obtained using the DSI scheme, probabilistic tractography, spherical deconvolution, and additional constraining masks (Figure 3). We localized the true positives and false negatives for each submission in terms of pathways in the validation case (Figure 4). At a false positive rate=0.1, the sensitivity was variable across different pathways and overall low (HCP=0.57, DSI=0.56). Almost all submissions label regions close to the injection site correctly, but most fail to reconstruct pathways far from it or that require splitting from the main trajectory (eg. brainstem and thalamic fibers). Majority voting analysis confirms this trend.

Discussion and Conclusion

Our results show that, when processing methods are tuned appropriately, it is possible to achieve similar tractography accuracy with the HCP and DSI schemes, even though the latter involves 2.8 times more directions and 3.3 times higher maximum b-value. Thus the HCP scheme represents an advantageous trade-off between accuracy and acquisition time. For many of the pipelines employed here, optimizing the methods with respect to accuracy for one seed/injection region did not guarantee optimal performance for another region. This highlights the importance of using anatomical studies from a variety of regions as guidance for tractography. The two injection sites used here project through similar white-matter pathways but reach those pathways from very different angles. The tracing data reveal complex systems of small bundles that travel within and jump between different pathways¹⁴. The present results confirm the limited accuracy of tractography when traveling longer distances and through bottle-neck regions, where fibres align and diverge¹⁵. Encouragingly, two teams could achieve consistently high performance in both training and validation datasets. In next steps, we will investigate which of their pre/post-processing and tractography methods led to this robustness. We expect our findings to have implications for analyzing the thousands of datasets acquired with the HCP scheme that will soon be publicly available.

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Figures

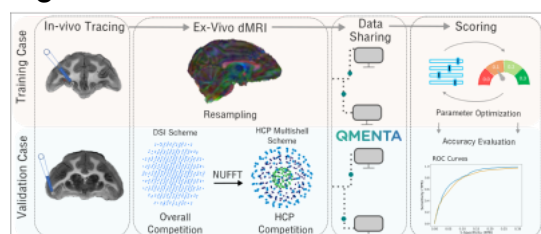


Figure 1. Challenge pipeline. Data from two monkey brains served as training and validation cases. For both we had in-vivo tracing with different injection sites in the frontal cortex, and ex-vivo dMRI acquired on a Cartesian grid (515 directions, max b-value=40,000s/mm²) and resampled through non-uniform fast Fourier transform (NUFFT) on the HCP multi-shell scheme. Data were shared via the Qmenta platform; participants could tune tractography parameters on the basis of the accuracy score obtained for the training data. Submissions for the validation case were then evaluated.

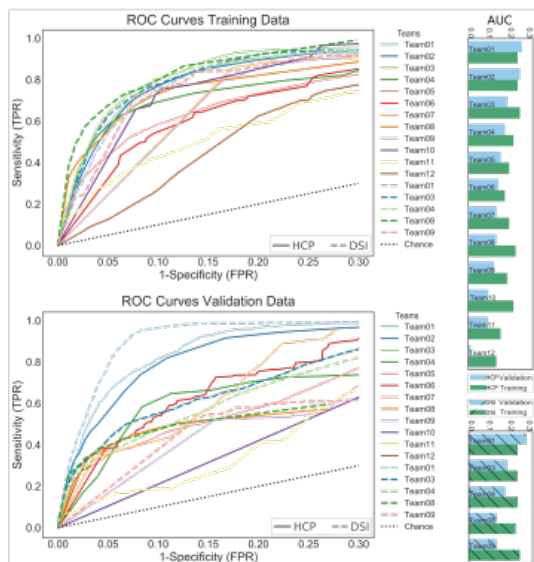


Figure 2. Receiver Operator Characteristic (ROC) curves and the corresponding Area Under the Curve (AUC) are shown for each submission for both training (top) and validation case (bottom), for HCP (solid lines) and Overall/DSI (dashed line) ranking. We set the maximum false positive rate (FPR) = 0.3, as previous studies showed this to be the maximum FPR that can be achieved by deterministic tractography methods⁹. Bar graphs show the AUC score for each team for the training (green) and validation (lightblue) case for HCP (top) and overall/DSI ranking (bottom).

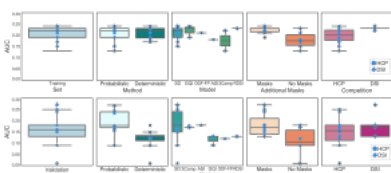


Figure 3. Area under the curve (AUC) scores for different tractography methods, diffusion models, masking strategies and acquisition schemes for training (top) and validation data (bottom) across all submissions. Overlay scatterplots show submissions for HCP (●) and overall/DSI (◆). SD= spherical deconvolution; 3Comp = three compartment model; ASI = asymmetry spectrum imaging; GQI = generalized Q-ball imaging; ODF-PP = orientation distribution function fingerprinting; RDSI = radial diffusion spectrum imaging.

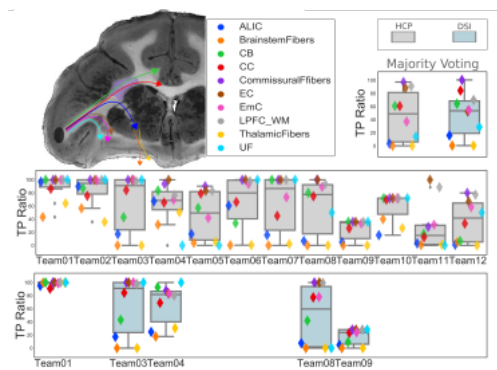


Figure 4. Schematic of the main pathways present in the tracing for the validation case (top-left). Boxplots and overlaid scatterplots show the ratio of true positive voxels for each bundle for each submission and for the majority vote (HCP: gray; overall/DSI: lightblue). All submissions were evaluated at FPR=0.1. ALIC=anterior limb of the internal capsule; CB=cingulum bundle; CC=corpus callosum; EC=external capsule; EmC=extreme capsule; LPFC_WM=lateral pre-frontal cortex white-matter; UF=uncinate fasciculus.

Submission	Team	Team Name	Preprocessing	ROC Sampling Strategy	Model	Method	Masked
1	1	Tracky McTrackface	Yes	Visitation Map	RUMBA-SD	Local/Probabilistic	Yes
2	2	TwoPantsCharged	No	Visitation Map	CSD	Local/Probabilistic	Yes
3	3	Accesschallenge	Yes	Visitation Map	MSMT-CSD	Local/Probabilistic	Yes
4	4	Xlink	Yes	FOD amp/ProbLength	3-Comp	Local/Probabilistic	Yes
5	5	Team7	No	Visitation Map	CSD	Global/Deterministic	No
6	6	Tractogram	No	Angle/FA/Step-size	AS	Local/Deterministic	No
7	7	SpaghettiBeans	Yes	Angle	MSMT-CSD	Local/Probabilistic	Yes
8	8	HAFI	No	Visitation Map	GQI	Local/Deterministic	Yes
9	9	Simulinius	Yes	Angle/FA	ODF-PP	Local/Deterministic	No
10	10	Tractography validation	Yes	Visitation Map	MSMT-CSD	Local/Probabilistic	No
11	11	The Upside Down	Yes	Angle	GQI	Local/Deterministic	No
12	12	BCGK	Yes	Angle	RL-CSD	Local/Deterministic	No
13	1	Tracky McTrackface	Yes	Visitation Map	RUMBA-SD	Local/Probabilistic	Yes
14	3	Accesschallenge	Yes	Visitation Map	MSMT-CSD	Local/Probabilistic	Yes
15	4	Xlink	Yes	FOD amp/ProbLength	3-Comp	Local/Probabilistic	Yes
16	9	Simulinius	Yes	Angle/FA	RDG	Local/Deterministic	No
17	8	HAFI	No	Visitation Map	GQI	Local/Deterministic	Yes

Table 1. Details of the methods used by each team. Model=diffusion model; Method=Tractography algorithm; Masks=use of additional masks to constrain tractography. 3-Comp=Three compartment model¹⁶; ASI= Asymmetry Spectrum Imaging¹⁷; CSD=constrained spherical deconvolution¹⁸; GQI=Generalized Q-ball Imaging¹⁹; MSMT-CSD=Multi Shell Multi Tissue Constrained Spherical Deconvolution^{20,21}; ODF-FP=ODF Fingerprinting²²; RDSI= Radial DSI²³; RL-SD=Richardson-Lucy Spherical Deconvolution²⁴; RUMBA-SD=Robust and Unbiased Model-Based Spherical Deconvolution²⁵.